

# Numerical simulation of long ship waves

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Joint SEAMOCS and CENS-CMA workshop  
Palmse 2007



# Outline of talk

Ship waves in coastal waters

Equations and numerical models

Influence of speed and depth variation on ship generated waves

CENS-CMA project: Ship waves in the Tallinn Bay area

Summary

# Wash waves from high speed vessels



HSS "Stena Discovery"

Top Speed:

40 knots (= 20.6 m/s)

Dimensions:

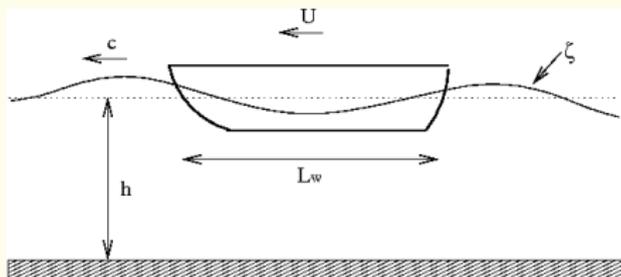
Length: 121.75 m

Width: 40.00 m

Draft: 4.80 m

- ▶ Waves from high speed vessels:
  - ▶ Long wave lengths and wave periods.
  - ▶ Large wave energy.
  - ▶ Qualitatively different from waves generated by conventional ships.
- ▶ Potentially dangerous for people on the shore or in small boats.
- ▶ May damage structures at the shore or moored vessels.
- ▶ May increase erosion and disturb marine habitats.

# Parameters for ship wave generation



- ▶ Length Froude number:  $F_L = \frac{U}{\sqrt{gL_w}}$ 
  - ▶ High speed vessels:  $F_L > 0.4$
  - ▶ Maximum wave resistance (hump speed):  $0.4 < F_L < 0.6$
- ▶ Depth Froude number:  $F_h = \frac{U}{\sqrt{gh}}$ 
  - ▶ Maximum wave resistance:  $F_h \approx 1$

# Ship classification

Displacement vessels:  $F_L < 0.4$   
- Hull is supported mainly by buoyancy force



Planing vessels:  $F_L > 1.0 - 1.2$   
- Hull is supported mainly by hydrodynamic pressure

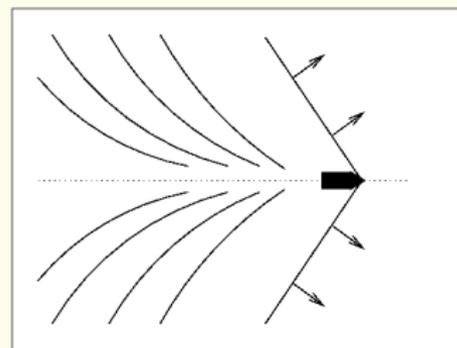
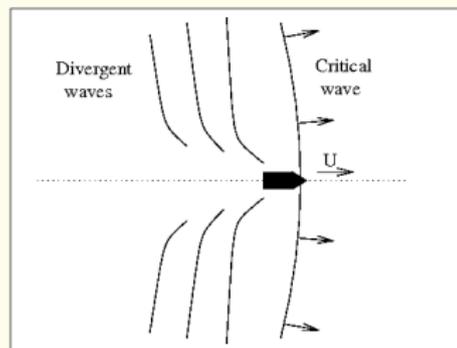
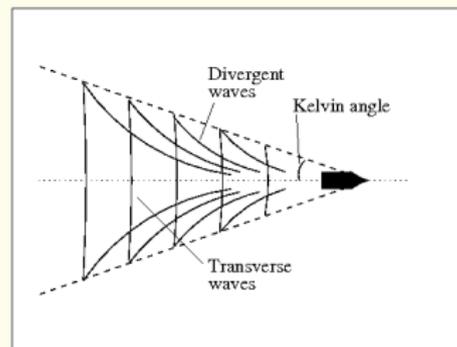


Semi-displacement vessels:  
 $0.4 - 0.5 < F_L < 1.0 - 1.2$



# Ship wave patterns

- ▶ Subcritical:  $F_h < 0.6$
- ▶ Critical:  $F_h \approx 1$
- ▶ Supercritical:  $F_h > 1.2 - 1.4$



Ship waves in coastal waters

**Equations and numerical models**

Influence of speed and depth variation on ship generated waves

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Summary

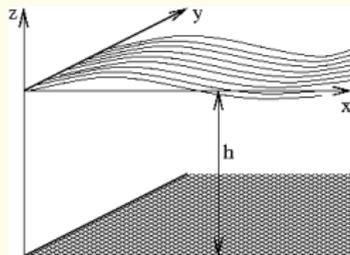
# Equations for inviscid, incompressible flow

- ▶ Continuity equation:

$$\nabla \cdot \mathbf{u} = \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

- ▶ Euler equation:

$$\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} = -\frac{1}{\rho} \nabla p + \mathbf{g}$$



- ▶ Dynamic and kinematic boundary conditions:

$$\begin{aligned} p &= p_a(x, y, t), & \text{at } z &= \eta(x, y, t) \\ w &= \frac{\partial \eta}{\partial t} + u \frac{\partial \eta}{\partial x} + v \frac{\partial \eta}{\partial y}, & \text{at } z &= \eta(x, y, t) \\ w &= u \frac{\partial h}{\partial x} + v \frac{\partial h}{\partial y}, & \text{at } z &= -h(x, y) \end{aligned}$$

## Strategies for numerical simulations

Numerical solution of Euler equations is possible, but at high computational cost.

- Restrict computational domain (or resolution)

Shallow water approximation:

- Reduce 3D equations to 2D equations by integrating over depth.

- Derive governing equations by expanding  $\mathbf{u}$  in terms of  $z$ .

Several different formulations may be derived from the primitive equations.

## fKdV and KP equations

Forced KdV (fKdV) equation (1D propagation)

$$\frac{\partial \eta}{\partial t} + \left(1 + \frac{3}{2}\eta\right) \frac{\partial \eta}{\partial t} + \frac{1}{6} \frac{\partial^3 \eta}{\partial x^3} = \frac{1}{2} \frac{\partial p_a}{\partial x}$$

Kadomtsev-Petviashvili (KP) equation (2D propagation)

$$\frac{\partial}{\partial x} \left[ \frac{\partial \eta}{\partial t} + \left(1 + \frac{3}{2}\eta\right) \frac{\partial \eta}{\partial t} + \frac{1}{6} \frac{\partial^3 \eta}{\partial x^3} \right] - \frac{1}{2} \frac{\partial^2 \eta}{\partial y^2} = \frac{1}{2} \frac{\partial^2 p_a}{\partial x^2}$$

Derived from KdV equation by relaxing 1D requirement.

# Boussinesq equations

- ▶ Formulate equations in terms of depth averaged velocity  $\bar{\mathbf{u}}$ , where  $\nabla_H = (\partial/\partial x, \partial/\partial y)$ .
- ▶ Continuity equation:

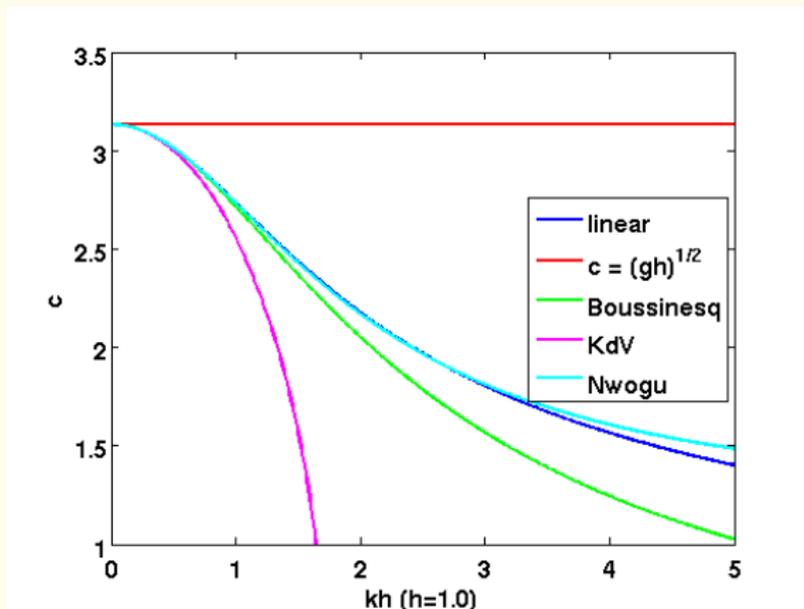
$$\frac{\partial \eta}{\partial t} + \nabla_H \cdot [(h + \eta)\bar{\mathbf{u}}] = 0$$

- ▶ Momentum equation:

$$\frac{\partial \bar{\mathbf{u}}}{\partial t} + (\bar{\mathbf{u}} \cdot \nabla_H)\bar{\mathbf{u}} = -\nabla_H \eta - \nabla_H p_a + \frac{1}{3}h^2 \nabla_H \nabla_H \cdot \left( \frac{\partial \bar{\mathbf{u}}}{\partial t} \right)$$

- ▶ Extensions of Boussinesq equations:
  - ▶ Formulations with depth variation include  $\nabla_H h$  terms.
  - ▶ Higher order formulations include dispersive terms with nonlinear corrections.

## Dispersion relation for long wave equations



Linear:  $c = \sqrt{(g/k) \tanh(kh)}$

Boussinesq: Classical Boussinesq formulation

Nwogu: Improved Boussinesq formulation

# Properties of long wave equations

KdV and KP equations:

- + Closed form (explicit) solutions exist for solitary and periodic waves.
- Restricted to unidirectional (KdV) or narrow angle (KP) of wave propagation.
- Poor dispersion relation for intermediate water depth.

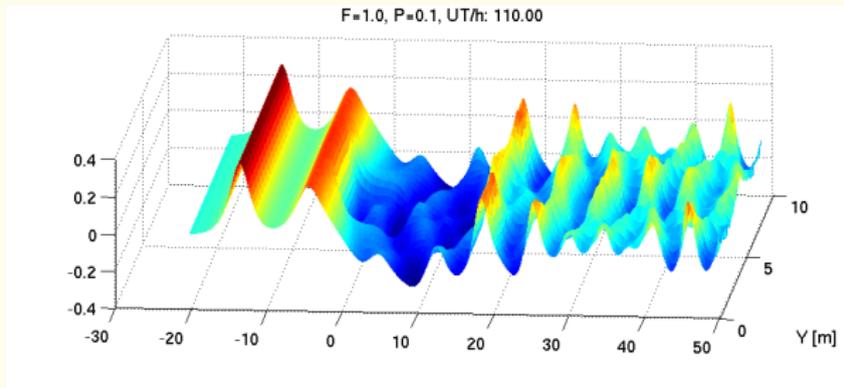
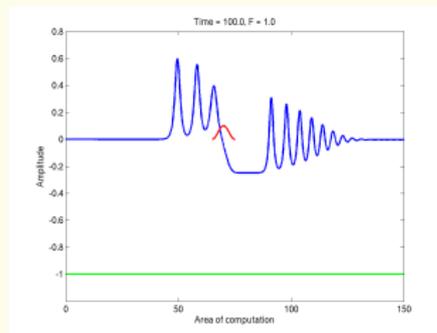
Boussinesq equations:

- No known closed form solutions.
- + No preferred direction of wave propagation.
- + Improved formulation with reasonable dispersion relation up to  $kh \approx \pi$ .

# Waves generated by a pressure disturbance

Waves generated by a moving pressure disturbance.

- ▶ Simple to implement.
- ▶ Unrealistic representation of wave field near the vessel.



Ship waves in coastal waters

Equations and numerical models

**Influence of speed and depth variation on ship generated waves**

CENS-CMA project: Ship waves in the Tallinn Bay area

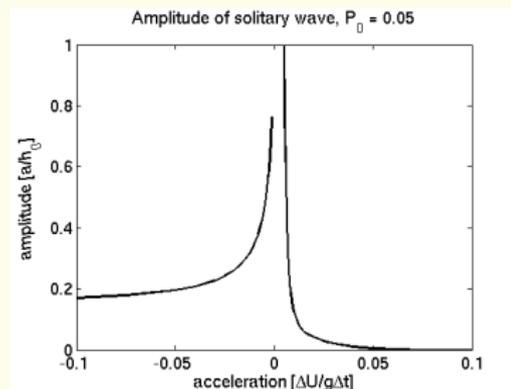
Summary

# Variable depth Froude number

- ▶ Motivation:  
Study waves generated during the transition between sub- and supercritical speed regimes.
- ▶ Method:  
Solve standard Boussinesq equations in one horizontal dimension (1-HD).
  - ▶ Weakly nonlinear equations:  $\epsilon = \mathcal{O}(\mu^2)$
  - ▶ Discretized with finite differences, using a staggered grid in time and space.
  - ▶  $F_h (= U/\sqrt{gh})$  changes due to linear variation in  $U$  or  $h$ .

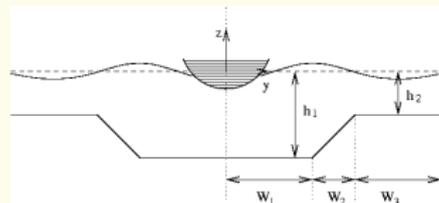
# Variable depth Froude number

- ▶ Results:  
Large amplitude solitary waves may be generated during a slow transition between sub- and supercritical speed.
- ▶ A precursor wave is always generated for a transition from super- to subcritical speed.
- ▶ The solitary wave may be trapped by the wave generating disturbance during a slow transition from sub- to supercritical speed.



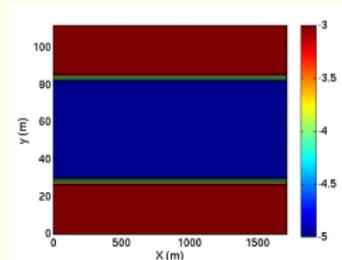
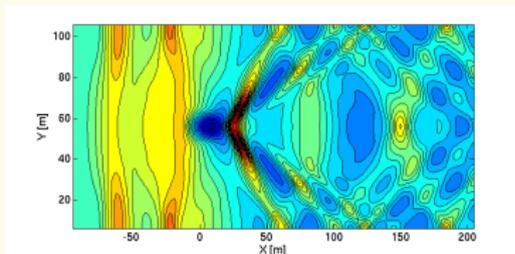
# Channels with a deep centre-line trench

- ▶ Motivation: Study waves generated by a vessel in a channel with a deep trench along the centre line.



- ▶ Method:  
Simulate waves using the Cornell University Long Wave model (COULWAVE).
  - ▶ 2-HD simulations.
  - ▶ Fully nonlinear equations:  $\epsilon = \mathcal{O}(1)$
  - ▶ Equations with improved dispersive properties.
  - ▶ Discretized with finite differences.
  - ▶ 4th order predictor-corrector method for time integration.

# Channels with a deep centre-line trench

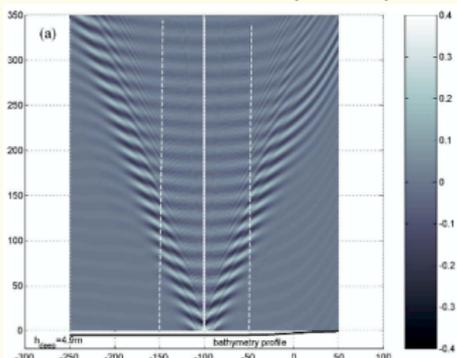


- ▶ Wave patterns with near critical or supercritical characteristics may occur, even if the vessel maintains a subcritical speed relative to the depth in the trench.
- ▶ When the leading precursor wave is long relative to the channel width, it can be described by cross-channel averaged theory.
- ▶ Large amplitude waves may sometimes occur on the shallow banks near the channel walls due to wave interactions in the downstream wave pattern.

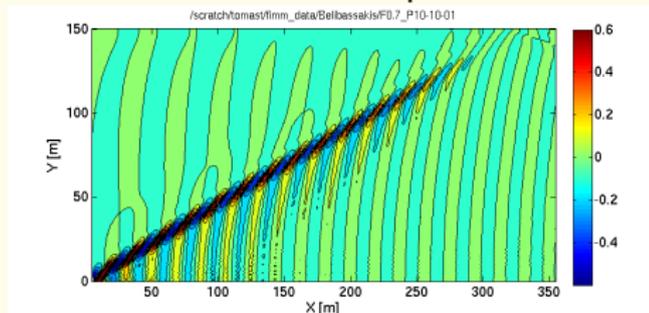
# Refraction of waves over a sloping bottom profile

Results for  $F_h = 0.7$

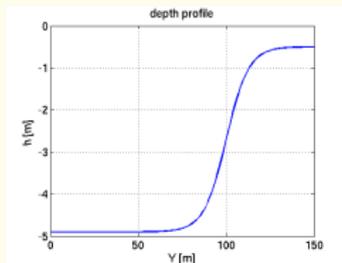
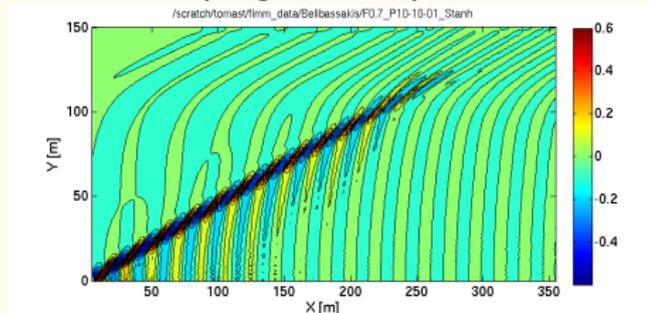
Belibassakis (2003)



Constant depth



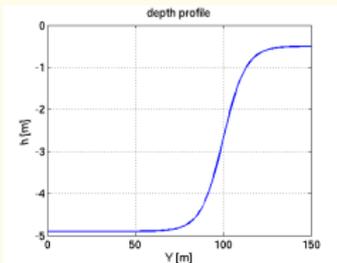
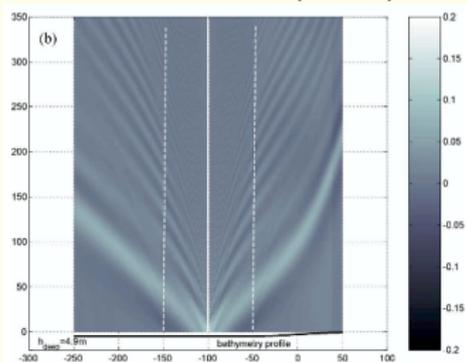
Sloping bottom profile



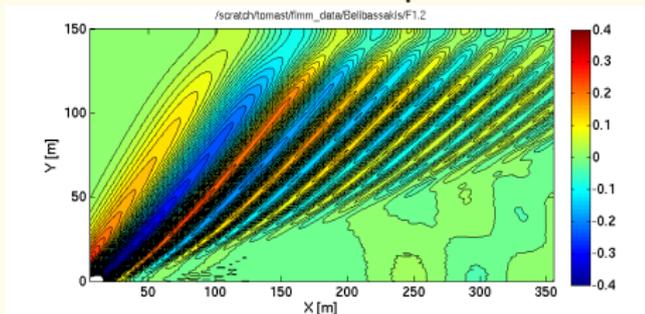
# Refraction of waves over a sloping bottom profile

Results for  $F_h = 1.2$

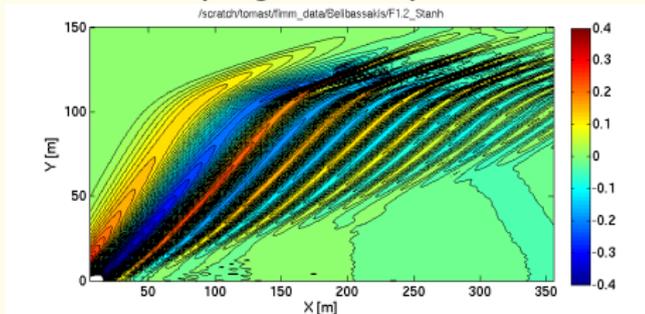
Belibassakis (2003)



Constant depth



Sloping bottom profile



Ship waves in coastal waters

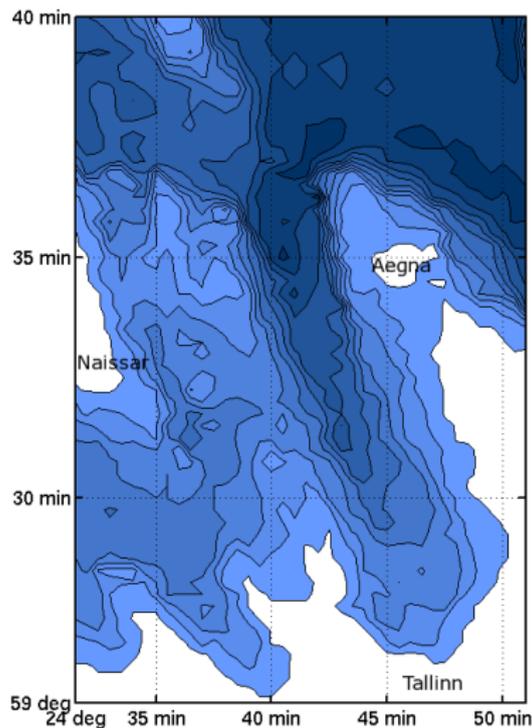
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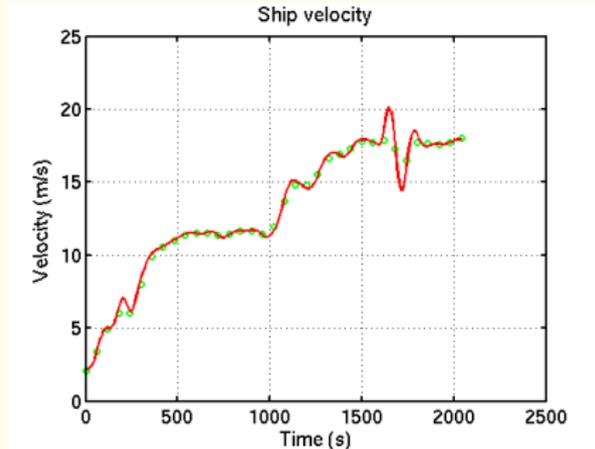
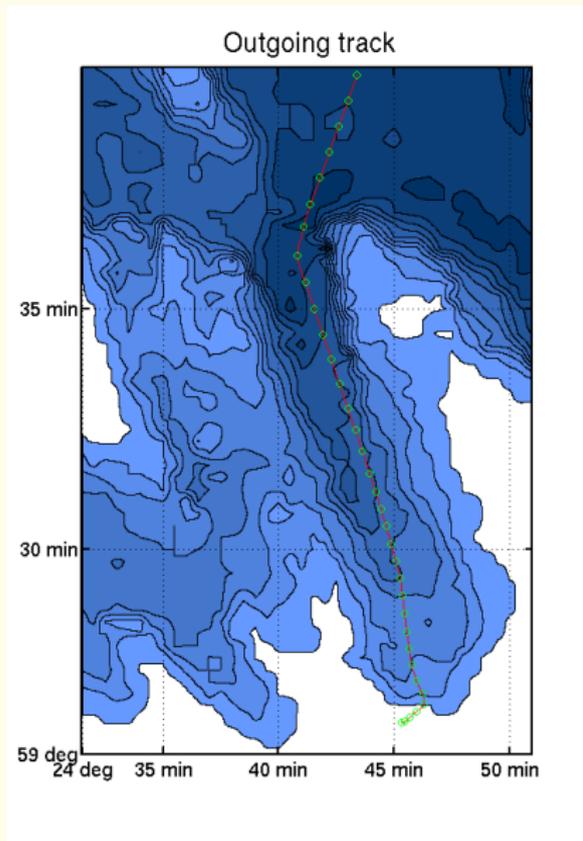
Summary

# Ship waves in the Tallinn Bay area



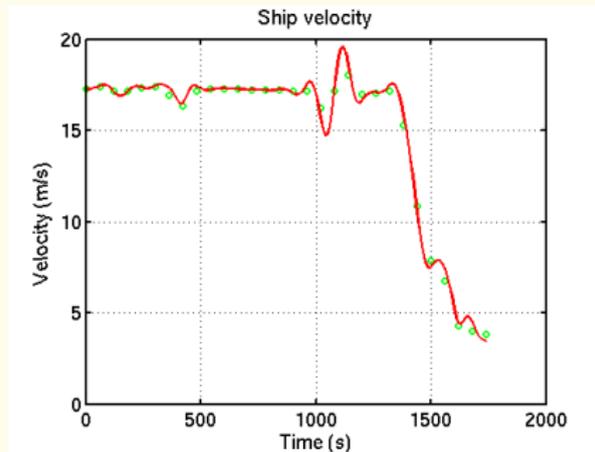
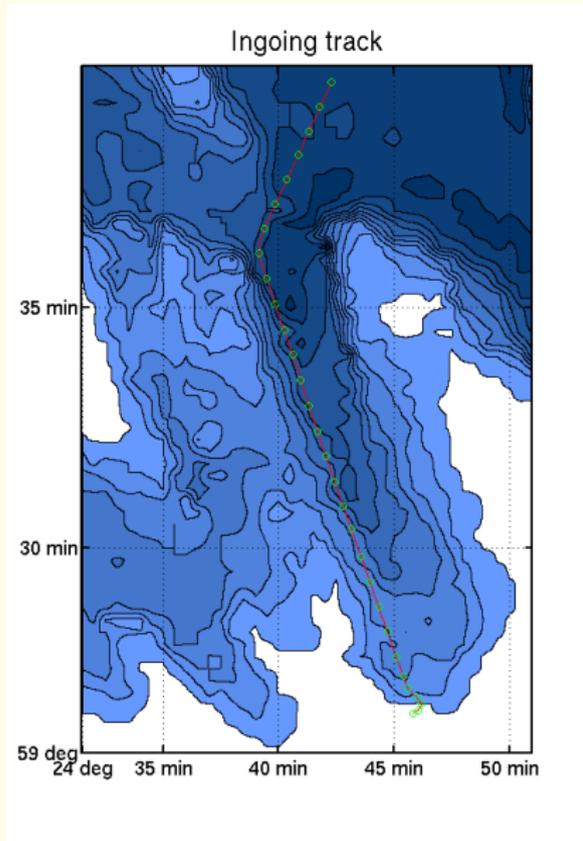
- ▶ Basin of about 16 km x 16 km
- ▶ Ship traffic follows NW - SE underwater valley, with depth ranging from 10 m to 90 m.
- ▶ Daily crossings (ingoing or outgoing)
  - ▶ 22 HSC/Catamaran
  - ▶ 8-10 Hydrofoil
- ▶ A natural laboratory for the study of long waves.
  - ▶ Also relevant for tsunami research.

# Ship track for outgoing ship



- ▶  $U \approx 12$  m/s in inner part of the bay.
- ▶  $U \approx 17$  m/s as the ship approaches Aegna.
- ▶ Turn outside Aegna may cause wave focusing.

# Ship track for ingoing ship



- ▶  $U \approx 17$  maintained almost the entire length of the bay.
- ▶ Ship track coincides with lateral slope of the underwater valley.

# Summary

- ▶ Long waves generated by high speed vessels are
  - ▶ a recent addition to the typical wave spectre in coastal areas.
  - ▶ a potential safety and environmental hazard.
- ▶ The long wave part of the ship wash is well described by the Boussinesq equations.
- ▶ For practical applications, particular attention should be placed on effects due to ship acceleration and maneuvering, as well as effects due to a variable bathymetry.